



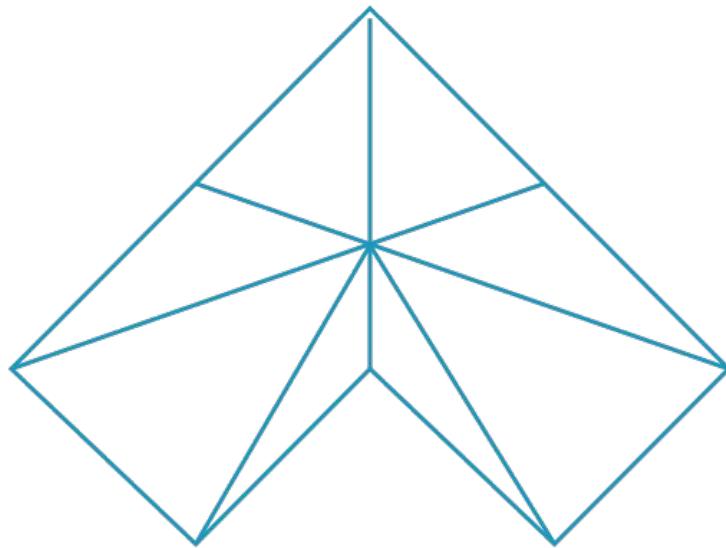
# Input fra en nørd

BIM AARHUS - 28/3/2019



# Jacob Frølund

Programmør | IT arkitekt  
IT projektleder | Scrum Master





# Agenda

- At tænke eksponentielt
- AI / ML
- Software udvikling

# At tænke eksponentielt



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# Matematisk

$$f(x) = 2x + 4$$

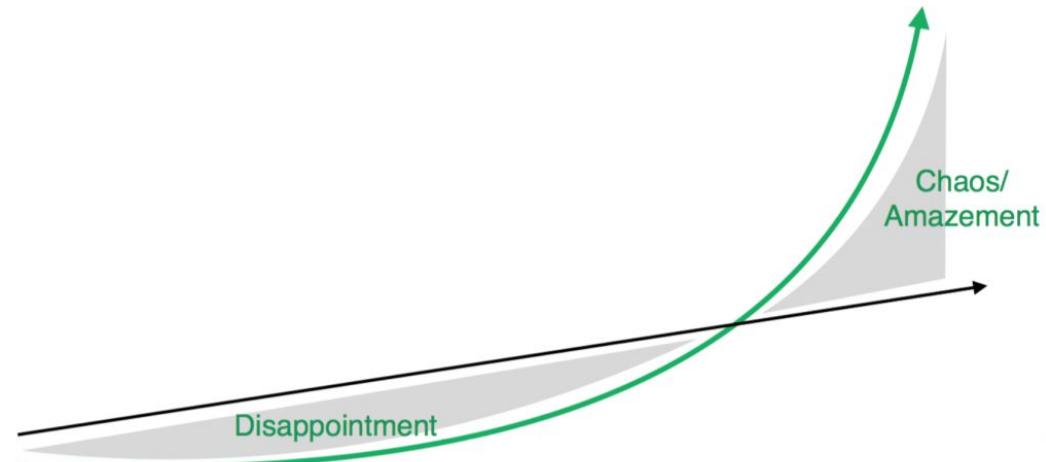
Lineær

$$f(x) = 2^x$$

Eksponentiel

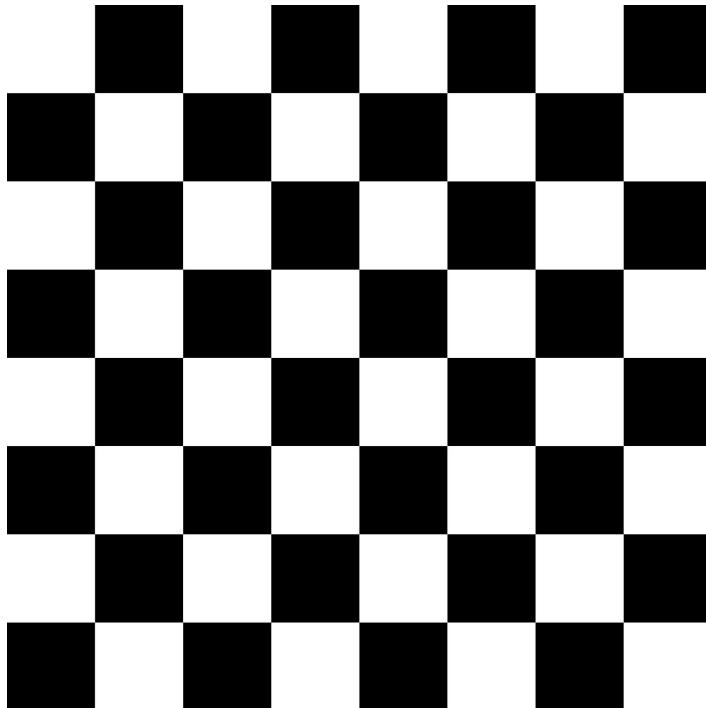
# Eksponentielt mod lineært

Deception of linear  
vs exponential



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# Opfindelsen af skak



Felt: 1 - Riskorn: 1

Felt: 2 - Riskorn: 2

Felt: 3 - Riskorn: 4

Felt: 4 - Riskorn: 8

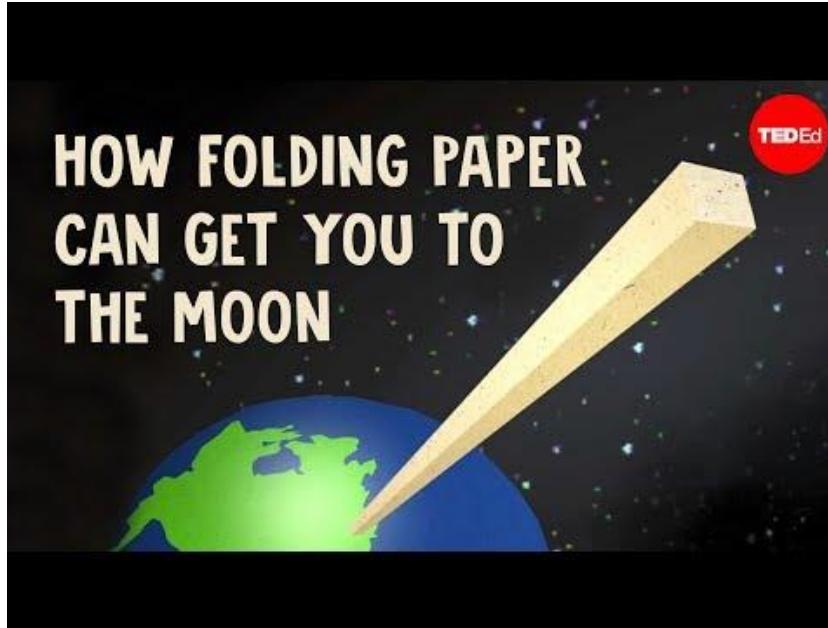
Felt 32: - Riskorn: 4.294.967.295

Felt 56: - Riskorn: 72.057.594.037.927.935

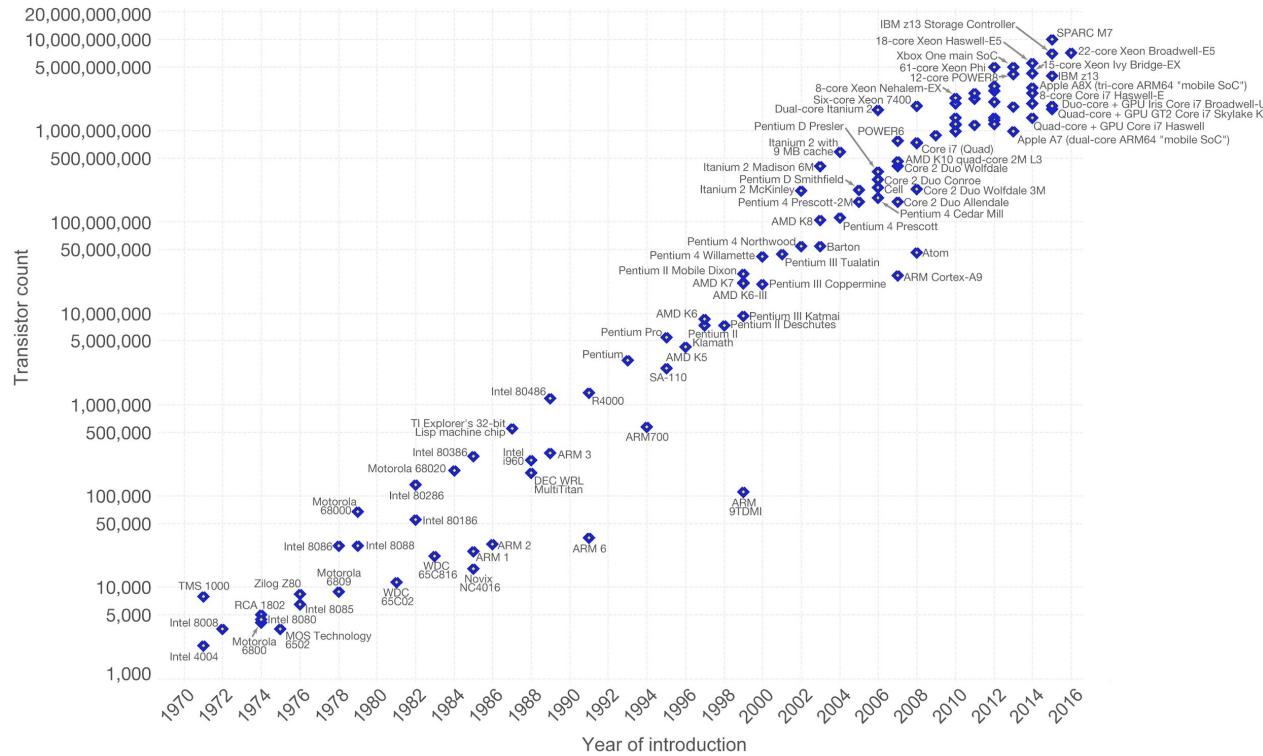
Felt 64: - Riskorn: 18.446.744.073.709.551.615

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# At foldepapir og nå månen



# Moore's law

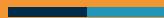


Data source: Wikipedia ([https://en.wikipedia.org/wiki/Transistor\\_count](https://en.wikipedia.org/wiki/Transistor_count))

The data visualization is available at [OurWorldInData.org](http://OurWorldInData.org). There you find more visualizations and research on this topic.

Licensed under CC-BY-SA by the author Max Roser.

AI / ML



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# Definition

**Algoritme** (a process or set of rules to be followed)

**Snæver AI** (narrow AI, is artificial intelligence that is focused on one narrow task)

**General AI** (would be capable of recursive self-improvement)

# Bubble sort



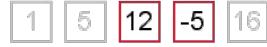
unsorted



$5 > 1$ , swap



$5 < 12$ , ok



$12 > -5$ , swap



$12 < 16$ , ok



$1 < 5$ , ok



$5 > -5$ , swap



$5 < 12$ , ok



$1 > -5$ , swap



$1 < 5$ , ok



$-5 < 1$ , ok



sorted

```
public void bubbleSort(int[] arr) {  
    boolean swapped = true;  
    int j = 0;  
    int tmp;  
    while (swapped) {  
        swapped = false;  
        j++;  
        for (int i = 0; i < arr.length - j; i++) {  
  
            if (arr[i] > arr[i + 1]) {  
                tmp = arr[i];  
                arr[i] = arr[i + 1];  
                arr[i + 1] = tmp;  
                swapped = true;  
            }  
        }  
    }  
}
```



# WAYMO

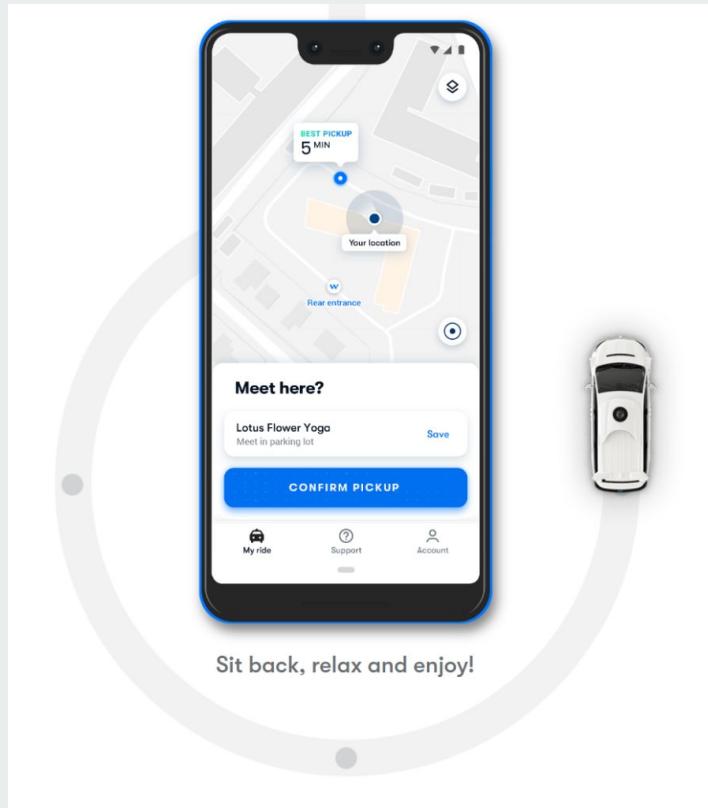
2009 - 10 ture af 100 miles uden  
afbrydelser.

2012 - 300.000 miles kørt - udvikling af egne  
sensorer.



2015 - Første tur på offentlig vej uden føre

2017 - Første produktions eksemplar af en  
selvkørende bil. Offentlig test i Phoenix



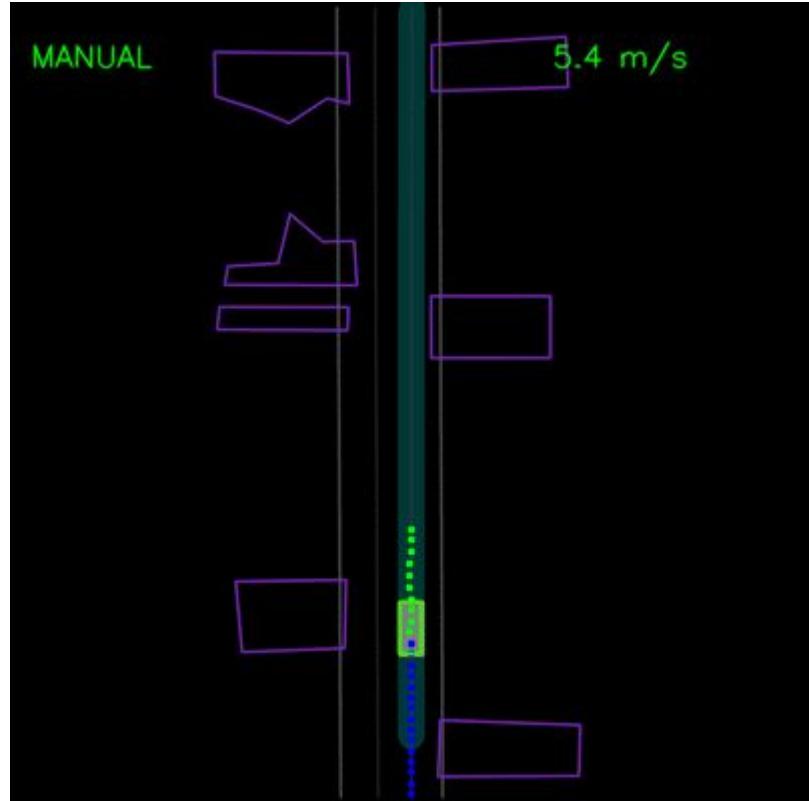
2018 - Waymo One lanceret i Phoenix

# Waymo sensors





# Simulation





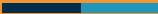
## **AlphaGo**

Lærte at spille ved at se på tusindvis af spil  
spillede af mennesker.

## **AlphaGo Zero**

lærte at spille go ved at spille tilfældige spil  
mod sig selv.

# Software udvikling





# Agilitet

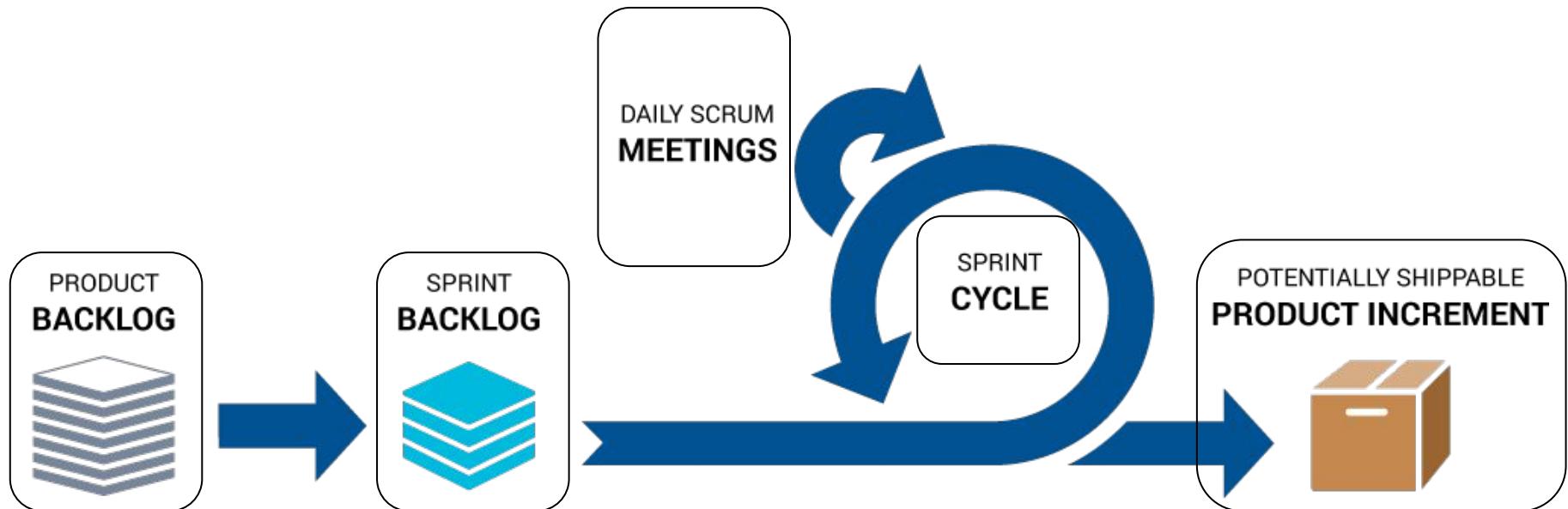
**Individuals and Interactions**  
over  
processes and tools

**Working Software**  
over  
comprehensive documentation

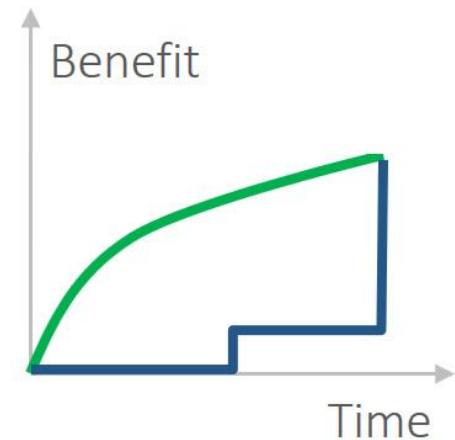
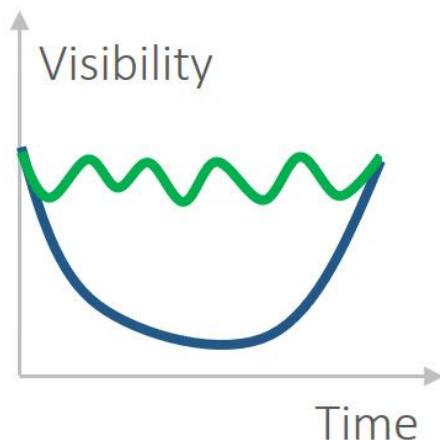
**Customer Collaboration**  
over  
contract negotiation

**Responding to Change**  
over  
following a plan

# Scrum



# Ønsked effekt



— traditional — agile

# 30% spild

Verden ændre sig og det  
er derfor svært at  
definere et fast mål.





# Spørgsmål?

Slides på liib.dk